

FORM PTO-1449
(REV. 7-80)U.S. DEPARTMENT OF COMMERCE
PATENT AND TRADEMARK OFFICEATTY. DOCKET NO.
40146/32:6APPLICATION NO.
10/649,116INFORMATION DISCLOSURE CITATION
(Uses several sheets if necessary)APPLICANT
Paul Bacchi and Paul S. FilipskiFILING DATE
August 26, 2003GROUP
3661

U.S. PATENT DOCUMENTS

EXAMINER INITIAL		DOCUMENT NUMBER									DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
m m	AA	6	6	1	8	6	4	5	09/09/03	Bacchi et al.		700	254		08/15/02
	AB	6	4	5	3	2	1	4	09/17/02	Bacchi et al.		700	245		08/02/01
	AC	6	4	3	8	4	6	0	08/20/02	Bacchi et al.		700	245		08/01/01
	AD	6	2	7	5	7	4	8	08/14/01	Bacchi et al.		700	245		05/14/99
	AE	6	2	5	6	5	5	5	07/03/01	Bacchi et al.		700	245		12/02/98
	AF	6	1	6	0	2	6	5	12/12/00	Bacchi et al.		250	559.29		08/27/98
	AG	6	1	1	3	1	6	5	09/05/00	Wen et al.		294	1.1		10/02/98
	AH	6	1	0	9	6	7	7	08/29/00	Anthony		294	103.1		05/28/98
	AI	6	1	0	5	4	5	4	08/22/00	Bacchi et al.		074	490.03		06/16/98
	AJ	6	0	9	8	4	8	4	08/08/00	Bacchi et al.		074	490.03		12/02/98
↓	AK	5	9	8	8	9	7	1	11/23/99	Fossey et al.		414	416		07/09/97

FOREIGN PATENT DOCUMENTS

EXAMINER INITIAL		DOCUMENT NUMBER									DATE	COUNTRY	CLASS	SUBCLASS	TRANSLATION	
															YES	NO
m m	AL	0	0	3	3	3	5	9	08.06.00	WO		H01L	21/00		X	
	AM	0	0	0	3	4	1	8	20.01.00	WO		H01L	21/00		X	
	AN	0	8	2	0	0	9	1	21.01.98	Europe		H01L	21/00		X	
↓	AO	9	7	4	5	8	6	1	04.12.97	WO		H01L	21/00		X	
	AP	9	7	4	4	8	1	6	27.11.97	WO		H01L	21/00		X	

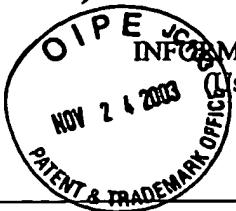
OTHER DOCUMENTS (Including Author, Title, Date, Pertinent Pages, etc.)

m m	AR	Motion Engineering, Inc., Advanced motion control semiconductor front-end applications, 1999, Internet, pp. 1-12.
	AS	Srinivasan, Modeling and performance analysis of cluster tools using petri nets, 1998, IEEE, pp. 394-403.
↓	AT	Song et al., Intelligent rehabilitation robotic system for the disabled and the elderly, 1998, IEEE, pp. 2682-2685.

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m - m	AA	5	9	8	0	1	8	8	11/09/99	Ko et al.	414	417	11/28/97	
	AB	5	9	4	4	4	7	6	08/31/99	Bacchi et al.	414	783	03/26/97	
	AC	5	8	7	0	4	8	8	02/09/99	Rush et al.	382	151	05/07/96	
	AD	5	8	1	0	9	3	5	09/22/98	Lee et al.	118	728	11/29/95	
	AE	5	7	6	5	4	4	4	06/16/98	Bacchi et al.	074	490.03		
	AF	5	7	4	1	1	1	3	04/21/98	Bacchi et al.	414	744.5		
	AG	5	6	9	7	7	5	9	12/16/97	Bacchi et al.	414	786		
	AH	5	6	6	9	6	4	4	09/23/97	Kaihotsu et al.	294	1.1		
	AI	5	5	3	8	3	8	5	07/23/96	Bacchi et al.	414	403		
	AJ	5	5	1	3	9	4	8	05/07/96	Bacchi et al.	414	783		
	AK	5	5	1	1	9	3	4	04/30/96	Bacchi et al.	414	783		

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m - m	AL	8	2	2	7	9	3	1	03.09.96	Japan	H01L	21/68	Machine		
	AM	0	6	6	9	6	4	2	30.08.95	Europe	H01L	21/00	X		
	AN	7	2	0	1	9	4	7	04.08.95	Japan	21	68	X		
	AO	7	1	5	3	8	1	8	16.06.95	Japan	21	68	X		
	AP	7	0	3	7	9	6	0	07.02.95	Japan	H01L	21/68	Abstract		

OTHER DOCUMENTS (Including Author, Title, Date, Pertinent Pages, etc.)

m - m	AR	Arai et al., Micro endeffector with micro pyramids and integrated piezoresistive force sensor, 1996, IEEE, pp. 842-849.
	AS	Hesselroth et al., Neural network control of a pneumatic robot arm, 1994, IEEE, pp. 28-38.
	AT	Brett et al., A tactile sensing technique for automatic gripping of compact shaped non-rigid materials, 1994, IEEE, pp. 5/1-5/5.

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EXAMINER INITIAL	DOCUMENT NUMBER	DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
m m m	AA 5 4 5 6 5 6 1	10/10/95	Poduje et al.	414	225	
	AB 5 3 8 7 0 6 7	02/07/95	Grunes	414	217	
	AC 5 3 8 2 8 0 6	01/17/95	Bacchi et al.	250	561	
	AD 5 3 3 2 3 5 2	07/26/94	Poduje et al.	414	225	
	AE 5 2 3 8 3 5 4	08/24/93	Volovich	414	779	
	AF 5 1 3 3 6 3 5	07/28/92	Malin et al.	414	744.8	
	AG 5 0 9 2 7 2 9	03/03/92	Yamazaki et al.	414	225	
	AH 4 9 3 8 6 0 0	07/03/00	Into	365	401	
	AI 4 9 0 0 2 1 4	02/13/90	Ben	414	416	
	AJ 4 7 1 7 1 9 0	01/05/88	Witherspoon	294	99.2	
	AK 4 6 3 9 0 2 8	01/27/87	Olson	294	34	

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EXAMINER INITIAL	DOCUMENT NUMBER	DATE	COUNTRY	CLASS	SUBCLASS	TRANSLATION	
						YES	NO
m m m	AL 7 0 2 2 5 0 2	24.01.95	Japan	21	68	Machine	
	AM 9 4 1 9 8 2 1	01.09.94	WO	H01L	21/00	Abstract	
	AN 6 1 5 5 3 6 6	03.06.94	Japan	B25J	19/00	Machine	
	AO 4 3 4 3 4 4 8	30.11.92	Japan	21	68	Machine	
	AP 4 2 7 7 6 4 7	02.10.92	Japan	H01L	21/68	Abstract	

OTHER DOCUMENTS (Including Author, Title, Date, Pertinent Pages, etc.)

m m m	AR	Mahalingam et al., Special challenges of robotic gripping in space, 1988, IEEE, pp. 581-586.
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M	M	AA	4	6	6	2	8	1	1	05/05/87	Hayden	414	433	
		AB	4	4	5	2	4	8	0	06/05/84	Maier et al.	294	104	
		AC	4	4	1	0	2	0	9	10/18/83	Trapani	294	34	
		AD	4	0	2	4	9	4	4	05/24/97	Adams et al.	198	394	
		AE	2	3	6	7	9	9	1	01/23/45	Bailey	294	34	
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m m	AA	6	2	9	8	2	8	0		10/02/01	Bonora et al.	700	218	09/28/98
m m	AB	6	1	1	6	8	4	8		09/12/00	Thomas et al.	414	754	11/26/97
m m	AC	5	9	8	0	1	8	7		11/09/99	Verhovsky	414	416	04/17/97
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m.m	AC	5	9	8	0	1	8	7		11/09/99	Verhovsky	414	416	04/17/97
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EXAMINER W. D. Deuel, Jr.DATE CONSIDERED 11/11/04

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